

OWA

Deployments of Floating LiDAR Systems

Offshore Wind Accelerator – Wakes and Wind Resource

UFLR – OWA Floating LiDAR Roadmap Update

July 2018





















Document Information

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FOREWORD

Floating LiDAR technology has been identified as a potential replacement for conventional meteorological masts, which have been prevalent in use for wind resource assessments of proposed offshore wind farms to date. A floating LiDAR system (FLS) offers a significant cost reduction over an offshore meteorological mast and has the flexibility of being redeployed at different locations. As floating LiDAR is a maturing technology, it requires defined industry best practice validation procedures to improve industry confidence in the performance of this type of device before it can be used commercially. The Offshore Wind Accelerator (OWA) Floating LiDAR Systems Roadmap was originally published in 2013 to define different stages of maturity and establish the prerequisites for floating LiDAR systems to satisfy these defined stages of maturity. The Carbon Trust on behalf of the OWA has commissioned a combined project team from DNV GL, Frazer-Nash Consultancy, Fraunhofer IWES and Multiversum Consulting to update the existing Roadmap to reflect the latest status of floating LiDAR systems using input from stakeholders across the industry.

This document will support the OWA FLS Roadmap update project by providing a comprehensive list of FLS deployments and gathering associated operational experience. Following contributions from a number of parties (including Wind Farm developers, OEMs, Consultants and Research Institutes) it has been possible to compile a list of deployment campaigns to date, with details of the campaign and operational experience gained, including breakdowns by geography. The information available for each deployment varies. In some cases, a comprehensive set of deployment information and analysis data has been placed in the public domain, with independent review of outcomes also reported; in others, limited information is available due to commercial sensitivities. In all cases the information available is provided here including associated references.

At the time of writing, the number of known FLS deployments, including trials and WRA deployments, totals 84. These consist of 13 FLS types deployed at approximately 40 locations, mostly in northern Europe but also including North America and Taiwan. Stage 2 maturity ("Pre-Commercial") has been independently reported for 7 systems. The majority of deployments to date have taken place since the publication of the roadmap document, which in itself underlines to requirement to provide an update to the roadmap.

The information contained in this document, together with the outcomes of the associated industry workshop held in London on the 23rd January 2018, informs the requirements for the subsequent stages to the OWA FLS Roadmap project.

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1. ACRONYMS

EOWDC	European Offshore Wind Deployment Centre	
FLS	Floating LiDAR System	
GSOE	Garden State Offshore Energy	
NAREC	National Renewable Energy Centre	
OEM	Original Equipment Manufacturer	
OWF	Offshore Wind Farm	
PNNL	Pacific Northwest National Laboratory	
WRA	Wind Resource Assessment	

2. INTRODUCTION

2.1 BACKGROUND

The Offshore Wind Accelerator (OWA) was initiated in 2008 by the Carbon Trust with the support of nine offshore wind development companies. The aim of the OWA is to reduce costs and increase the efficiency of offshore wind farms and to develop best practice in the industry.

Floating LiDAR technology has been identified as a potential replacement for conventional meteorological masts which have been prevalent in use for wind resource assessments of proposed offshore wind farms to date. A floating LiDAR system (FLS) offers a significant cost reduction over an offshore meteorological mast and has the flexibility of being redeployed at different locations. As floating LiDAR is a maturing technology, it requires defined industry best practice validation procedures to improve industry confidence in the performance of this type of device before it can be used commercially. The OWA Floating LiDAR Systems Roadmap [R1] was originally published in 2013 to define different stages of maturity and establish the prerequisites for floating LiDAR systems to satisfy these defined stages of maturity. The Carbon Trust on behalf of the OWA has commissioned an update to the existing Roadmap to reflect the latest status of floating LiDAR systems using input from stakeholders across the industry.

2.2 OBJECTIVE

This document will support the OWA FLS Roadmap update by providing a comprehensive list of FLS deployments. Following contributions from a number of parties (including Wind Farm developers, OEMs, Consultants and Research Institutes) it has been possible to compile a list of deployment campaigns to date, with details of the campaign and operational experience gained, including breakdowns by geography.

It should be noted that the information presented is based on information available and shared by stakeholder parties at the time of writing, but it is not possible to guarantee that all FLS deployments have been listed.

2.3 DOCUMENT STRUCTURE

The document comprises 4 sections:

2. Introduction

3. <u>Deployments Overview</u>

This section presents a brief overview of the number of systems and deployments, and of reported maturity stages.

4. <u>Detailed Deployments List</u>

This section contains a detailed list of all FLS deployments sorted by FLS type. The entry for each deployment contains information including date, location, organisations involved and resources as well as an image and an account of user experiences during the campaign (where available). Each deployment is assigned a reference number (e.g. D1) which is referred to throughout the document.

5. <u>Deployments by Location</u>

Deployments are sorted geographically and shown on a map.

6. G	General	Operational	Experience	Feedback
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From the feedback received, a number of challenges were identified which are relevant to deployment of FLS in general and not specific to individual deployments. These are listed in this section.

3. **DEPLOYMENTS OVERVIEW**

At the time of writing, the number of known FLS deployments, including trials and WRA deployments, totals 84. These consist of 13 FLS types deployed at approximately 40 locations, mostly in northern Europe but also including North America and Taiwan. Stage 2 maturity ("Pre-Commercial") has been independently reported for 7 systems.

The FLS types, their first deployment dates, and any independently reported maturity claims are summarised in Table 1 below. A detailed list of deployments by FLS type is included in Section 4. To convey the growth in the industry's use of the technology, the number of FLS deployments at any one time is shown in Figure 1. A geographical view of the distribution of FLS deployments is provided by the map figures in Section 5.

System Name	First Deployment	LiDAR Used	Independently Reported Maturity Stage
AXYS FLIDAR WindSentinel	2009	ZephIR 300, Windcube v2	Stage 2
SeaZephir	2009	ZephIR 300	
AXYS FLIDAR 4M (FLIDAR)	2011	ZephIR 300, Windcube v2	Stage 2
EOLOS FLS200	2013	ZephIR 300	Stage 2
DeepCLiDAR	2013	Windcube v2	Stage 2 ¹
Fraunhofer IWES Wind LiDAR Buoy	2013	Windcube v2, ZephIR 300	Stage 2
Nass&Wind M3EA	2014	Windcube v2	
Fugro Oceanor SEAWATCH	2014	ZephIR 300	Stage 2
Babcock FORECAST	2014	ZephIR 300	Stage 2
SeaLIDAR	2015	ZephIR 300	
Eolfi Spar	2016	Diabrezza (Mitsubishi Electric) or other	
AKROCEAN WINDSEA	2017	Windcube v2, Zephir 300	
DEWI with Leosphere	2017	Windcube v2	

¹ Maturity stage independently reported following a 5 month trial duration only.

Table 1: Summary of Floating LIDAR System types by first deployment dates, with associated maturity stages.

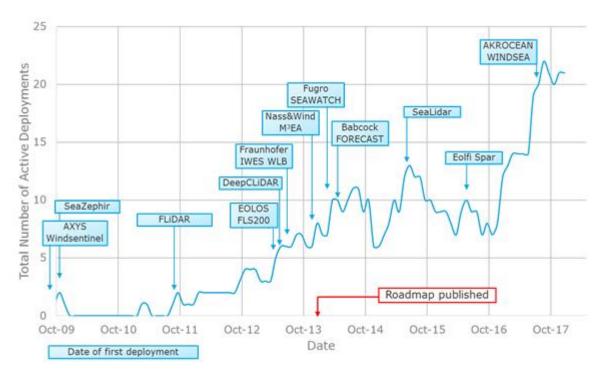


Figure 1: Indicative timeline showing number of deployed FLS systems. The date of the original OWA FLS Roadmap publication is shown in red.

4. DETAILED DEPLOYMENTS LIST

The following pages contain details of all known FLS deployments at the time of writing. It should be noted that the information presented is based on information available and shared by stakeholder parties at the time of writing, but it is not possible to guarantee that all FLS deployments have been listed.

Entries are sorted by FLS type, starting with the earliest initial deployment:

Index	FLS	Date of First Deployment	Number of deployments to date
4.1	AXYS FLiDAR WindSentinel	October 2009	24
4.2	SeaZephIR	November 2009	3
4.3	AXYS FLIDAR 4M	September 2011	12
4.4	EOLOS FLS200	May 2013	5
4.5	DeepCLiDAR	June 2013	2
4.6	Fraunhofer IWES Wind LiDAR Buoy	August 2013	10
4.7	Nass&Wind M³EA	January 2014	2
4.8	Fugro OCEANOR SEAWATCH	April 2014	19
4.9	Babcock FORECAST	May 2014	2
4.10	seaLIDAR	July 2015	1
4.11	Eolfi Spar	May 2016	1
4.12	AKROCEAN WINDSEA	July 2017	2
4.13	DEWI with Leosphere	September 2017	1

4.1 AXYS FLIDAR WINDSENTINEL

FLS OEM: AXYS Technologies Inc.

LiDAR Type: The AXYS FLiDAR WindSentinel was previously known just as WindSentinel™ and carried a Vindicator® laser wind sensor. It was renamed in 2014 and now supports either a ZephIR 300M, WINDCUBE v2 Offshore LiDAR, or a combination of both.

Greyed-out rows indicate known deployments where further detail cannot be provided due to commercial sensitivity.

Ongoing deployments as of February 2018 are marked with an asterisk (*). The duration reported in these cases is the number of months from the deployment date to February 2018.

Deployments

Ref	Deployment Date	Duration (months)	Location	Campaign Type
D1	October 2009	1	Race Rocks, Strait of Juan	Trial
			de Fuca, Canada	
D2	October 2011	18	Lake Michigan, USA	WRA
	February 2012	23		WRA
D3			New Jersey, USA	
D4	May 2013	12	Taiwan	WRA
D5	September 2013	36	California	WRA
D6	July 2014	12	Demowfloat, Portugal	WRA
D7	November 2014	12	Virginia Beach, Virginia, USA	WRA
D8	April 2015	1	National Renewable Energy Centre (NAREC), North Sea	Trial
D9	April 2015	1	National Renewable Energy Centre (NAREC), North Sea	Trial
	May 2015	33*	France	WRA
D10	June 2015	5	FINO1 Met. Mast, German Trial Bight, North Sea	
D11	September 2015	6	West of Duddon Sands wind farm zone, Irish Sea, UK	Trial
	October 2016	16*	Taiwan	WRA
D12	December 2016	14*	Bay of St Brieuc, France	WRA
	January 2017	1	USA	Trial
	July 2017	2	Taiwan	Trial
	July 2017	2	Taiwan	Trial
	July 2017	3	Taiwan	Trial
D13	July 2017	8*	East Coast USA WRA	
	August 2017	2	UK Trial	
D14	September 2017	5*	Taiwan	WRA
	October 2017	4*	Taiwan	WRA
	November 2017	3*	Taiwan	WRA
	April 2018	Not started	USA	WRA

D1. FLiDAR WindSentinel Trial, 2009

FLS OEM	AXYS Technologies Inc.	Other organisations		
Start/End Date	October – November, 2009	Length of campaign	1 month	
Location	Race Rocks, Strait of Juan	de Fuca, Canada		
Image	Image taken from WindSentinel Field Test Data Summary [R2]			
FLS	FLiDAR WindSentinel™			
LiDAR Type	Vindicator® laser wind sen	sor		
Purpose of deployment	Trial			
Description	The AXYS WindSentinel™ performed a comparison test with a land mounted system approximately 700 meters away. The FLS was instrumented with meteorological sensors, motion sensors and a Vindicator® laser wind sensor. The land mounted system was also instrumented with standard meteorological instruments and an identical Vindicator® LiDAR.			
OWA Roadmap Maturity Claim	N/A (Pre-Roadmap)			
Operational experience	Average surface wind speeds of up to 17.7m/s and 200m height wind speeds of 22.78m/s were recorded. The WindSentinel™ platform saw maximum wave heights of over 4 meters, ocean currents over 6 knots.			
Resources	WindSentinel Field Test Data Summary [R2]			
	Deployment details and experiences contributed by AXYS Technologies.			

D2. FLiDAR WindSentinel Great Lakes WRA 2011 -2013

FLS OEM	AXYS Technologies Inc.	Other organisations	Mic Ene Univ Mic Inst	chigan Alternative and Renewable ergy Center (MAREC) versity of Michigan chigan Memorial Phoenix Energy citute (MMPEI) chigan Natural Features Inventory of Michigan State University Extension
Start/End Date	October 2011 – April 2013	Length of campaign		months
Location	Lake Michigan, USA		<u> </u>	
Image	Massas Thomas Control of the Control			Image taken from Great Lakes Offshore Wind Resource Assessment Project Case Study [R3].
FLS	FLiDAR WindSentinel™			
LiDAR Type	Vindicator® laser wind sensor			
Purpose of Deployment	WRA			
Description	The objective of the project was to field test FLS technology to improve understanding of offshore wind resources as well as other physical, biological and environmental conditions on the Great Lakes as precursor activity to the future development of offshore wind energy technology.			
OWA Roadmap Maturity Claim	N/A (Pre-Roadmap)			
Operational experience	This campaign included the first towed deployment of a commercial FLS and the first jack up barge deployment of a system. Winds of up to 26 m/s and gusts of 29.9 m/s, and peak waves of around 10 m were experienced.			
Resources	Great Lakes Wind Res	source Assessmer	it Pro	ject Case Study [R3]
	Grand Valley State University: Lake Michigan Offshore Wind Assessment Project [R4] Deployment details and experiences contributed by AXYS Technologies,			
	Deployment details a	nu experiences co	מוטות	futed by AATS Technologies,

D3. FLiDAR WindSentinel WRA, New Jersey, 2013

ELC OFNA	LANGE T. L	O.I.	e: 1
FLS OEM	AXYS Technologies Inc.	Other organisations	Fisherman's Energy
		Organisacions	BOEM
Start/End Date	February 2012 – January	Length of	23 months
	2014	campaign	
Location	New Jersey, USA		
Image	Image provided by AXYS To	echnologies	
FLS	FLiDAR WindSentinel™		
LiDAR Type	Vindicator® laser wind sen	sor	
Purpose of Deployment	WRA		
Description	"With a year of preparations and near-shore testing, the buoy was relocated from a test site near Atlantic City to an offshore area leased from the U. S. Department of Interior's Bureau of Ocean Energy Management (BOEM). Located eleven miles southeast of Atlantic, NJ, this site is within the Mid-Atlantic Wind Energy Area, in an area Fishermen's Energy proposed to build a 350MW wind farm." [R6]		
OWA Roadmap Maturity Claim	N/A (Pre-Roadmap)		
Operational experience	N/A		
Resources	OffshoreWIND.biz press release [R5]		
	AXYS Technologies press re	elease [R6]	

D4. FLiDAR WindSentinel WRA, Taiwan, 2013

FLS OEM	AXYS Technologies Inc.	Other organisations	National Cheng Kung University
Start/End Date	May 2013 – May 2014	Length of campaign	12 months
Location	Taiwan		
Image	Image provided by AXYS To	echnologies	
FLS	FLiDAR WindSentinel™		
LiDAR Type	Vindicator® laser wind sen	sor	
Purpose of Deployment	WRA		
Description	The objective of the campaign was to support Taiwan's planned development of 3 GW of offshore wind projects.		
OWA Roadmap Maturity Claim	N/A (pre-roadmap)		
Operational experience	N/A		
Resources	AXYS Technologies press release [R7]		
	Deployment details contrib	buted by AXYS.	

D5. FLiDAR WindSentinel WRA, California, 2013

	T			
FLS OEM	AXYS Technologies Inc.	Other	Sound & Sea Technology	
		organisations	US Navy	
			DNV GL	
Start/End Date	September 2013 –	Length of	36 months	
	September 2016	campaign		
Location	California, USA			
Image				
ri c	Image taken from AXYS ne FLiDAR WindSentinel™	ws [R8]		
FLS				
LiDAR Type	Vindicator® laser wind sen	sor		
Purpose of Deployment	WRA			
Description	N/A			
OWA Roadmap Maturity Claim	N/A (pre-roadmap)			
Operational experience	N/A			
Resources	AXYS Technologies press release [R8]			
	Deployment details contrib	outed by AXYS.		

D6. FLiDAR WindSentinel WRA, Portugal, 2014

FLS OEM	AXYS Technologies Inc.	Other organisations	EDP Inovacao
Start/End Date	July 2014 – July 2015	Length of campaign	12 months
Location	Demowfloat, Portugal		
Image	Image provided by AXYS To	echnologies	
FLS	FLiDAR WindSentinel™		
LiDAR Type	Vindicator® laser wind sen	sor	
Purpose of Deployment	WRA		
Description	prototype floating wind tu	rbine, support the	onitor the performance of a e development of new assessments and to refine the wind
OWA Roadmap Maturity Claim	N/A		
Operational experience	The system survived a maj waves 10 metres high.	or storm with gal	e force winds gusting 90km/hr and
Resources	AXYS Technologies press release [R9]		
	Deployment details and ex	periences contrib	outed by AXYS Technologies.

D7. FLiDAR WindSentinel WRA, Virginia Beach, 2014-2016

	1	1		
FLS OEM	AXYS Technologies Inc.	Other organisations	PNNL	
Start/End Date	November 2014 – November 2015	Length of campaign	12 months	
Location	Virginia Beach, Virginia, US	SA		
Image	Image taken from PNNL De	eployment Plan [F	R10]	
FLS	FLiDAR WindSentinel™			
LiDAR Type	Vindicator® laser wind sen	sor		
Purpose of Deployment	WRA.			
Description	Deployments made to address the lack of publicly available long-term meteorological observations in US waters and to aid future development of offshore wind energy in the US. [R10]			
OWA Roadmap Maturity Claim	N/A			
Operational experience	N/A			
Resources	PNNL Wind-Profiling LiDAR Buoy Deployment Plan [R10]			

D8. and D9. FLiDAR WindSentinel Trial, NAREC, 2015

FLS OEM	AXYS Technologies Inc.	Other organisations	DNV GL (Independent assessor)	
		_	NAREC	
Start/End Date	April 2015 – May 2015	Length of campaign	1 month	
Location	National Renewable B	Energy Centre (NA	AREC), North Sea	
Image			NAREC Met. Mast. Image taken from Validation Assessment [R11].	
FLS	AXYS FLIDAR WindSer		11	
LiDAR Type	ZephIR 300 LiDAR and	a vindicator ivik-ii		
Purpose of Deployment	Trial			
Description	Two FLS deployed.			
	"An evaluation of the AXYS WindSentinel Floating LiDAR system was completed by comparing its measurements against data of a Reference Met Mast at the British Narec NOAH offshore test site. Sufficient data in terms of WS data completeness and coverage were collected to allow an assessment of this predeployment validation in line with the Roadmap." [R11]			
OWA Roadmap Maturity Claim	Stage 2 maturity inde	pendently report	ed (in combination with [D10])	
Operational experience	N/A			
Resources	DNV Validation Assessment NAREC [R11]			
	DNV Validation Asses	sment FINO1 [R1	2]	

D10. FLiDAR WindSentinel Trial, FINO1, 2015

_,	T			
FLS OEM	AXYS Technologies	Other organisations	DNV GL (Independent assessor)	
	Inc.		NORCOWE	
Start/End Date	June 2015 –	Length of	5 months	
	November 2015	campaign		
Location	FINO1 Met. Mast, Ge	rman Bight, North	n Sea	
Image	Image taken from DNV GL Independent Assessment [R12]			
FLS	AXYS FLiDAR WindSentinel™			
LiDAR Type	ZephIR 300M LiDAR (ZephIR 300M LiDAR (x2)		
Purpose of Deployment	Trial			
Description	AXYS Technologies Inc. (AXYS or the Client) commissioned GL Garrad Hassan Deutschland GmbH ("GHD"), part of the DNV GL group ("DNV GL") to carry out an independent assessment of an AXYS FLIDAR Windsentinel offshore validation, executed over a 5 month period next to the FINO1 Offshore Research Platform in German North Sea waters.			
OWA Roadmap Maturity Claim	Stage 2 maturity inde	ependently report	ed (in combination with [D8])	
Operational experience	FLS unit experienced heights of 5.9m and r	_	ge winds up to 26.4m/s, significant wave eights up to 10.7m.	
Resources	DNV Independent Assessment [R12]			
	Deployment details a	nd experiences co	ontributed by AXYS Technologies.	

D11. FLiDAR WindSentinel Trial, West of Duddon Sands, 2015

FLS OEM	AXYS Technologies	Other	Ørsted
TES GEIVI	Inc.	organisations	
			DNV GL (Independent assessor)
			Scottish Power (Iberdrola)
Start/End Date	September 2015 – March 2016	Length of campaign	6 months
Location	West of Duddon Sand	ds wind farm zone	e, Irish Sea, UK
Image			
516	Image taken from DNV GL Validation Report [R13] AXVS FLIDAR WindSentinel		
FLS	AXYS FLiDAR WindSentinel		
LiDAR Type	ZephIR 300M LiDAR a	ind Vindicator MK	(-III
Purpose of Deployment	Trial		
Description	"An independent evaluation of the AXYS FLiDAR 6M Buoy employing a ZephIR 300 type LiDAR (FLIDAR 6M single-ZephIR, formerly known as WindSentinel) was completed by DNV GL in in assessing its reliability and comparing its wind measurements from the buoy mounted ZephIR LiDAR against data from the WoDS Reference Met Mast (WRMM) in the Irish Sea." [R13]		
OWA Roadmap Maturity Claim	Stage 2 maturity independently reported		
Operational experience	FLS unit experienced 10-minute average winds up to 29.8 m/s, significant waves of Hs = 5.0m and max waves up to 9.4m		
Resources	Image taken from DNV GL Validation Report [R13]		
	Deployment details a	nd experiences co	ontributed by AXYS Technologies.

D12. AXYS FLIDAR 6M St Brieuc WRA, 2016-2018

FLS OEM Start/End Date	AXYS Technologies Inc. December 2016 – December 2018 (anticipated)	Other organisations Length of campaign	Scottish Power Renewables (Iberdrola) RES Ailes Marines 14 months*	
Location	St Brieuc, Brittany, Fr	ance		
Image	Image provided by A	XYS Technologies		
FLS	AXYS FLiDAR WindSentinel™			
LiDAR Type	ZephIR 300M LiDAR			
Purpose of Deployment	WRA.			
Description	Part of the energy assessment for the Bay of Saint-Brieuc commercial offshore wind farm development managed by Ailes Marines.			
OWA Roadmap Maturity Claim	N/A			
Operational experience	Favourable weather conditions meant installation was very quick.			
Resources	Deployment details and experiences contributed by Iberdrola (Scottish Power) and AXYS Technologies.			

^{*} The duration reported is the number of months from the deployment date to February 2018.

D13. AXYS FLiDAR Windsentinel USA WRA, 2017-2019

FLS OEM	AXYS Technologies Inc.	Other organisations	Ørsted	
Start/End Date	July 2017 – July 2019 (anticipated)	Length of campaign	8 months*	
Location	East Coast USA			
Image	No image available			
FLS	FLiDAR WindSentinel	тм		
LiDAR Type	ZephIR 300 LiDAR			
Purpose of Deployment	WRA.			
Description	LiDAR units were validated onshore to capture the required data range and offshore trial undertaken against met mast. Validation continues to prove useful as extended SAT Internal Validation carried out by Ørsted.			
OWA Roadmap Maturity Claim	N/A			
Operational .	Successful deployment.			
experience	Good co-operation from site team.			
	Tech challenges overcome with relative efficiency.			
	Supplier open to adaptions to Ørsted's specifications.			
Resources	Deployment details and experiences contributed by Ørsted.			

^{*} The duration reported is the number of months from the deployment date to February 2018.

D14. FLiDAR WindSentinel WRA, Taiwan, 2017-2019

FLS OEM	AXYS Technologies Inc.	Other organisations	Ørsted (developer)	
Start/End Date	September 2017 – September 2019 (anticipated)	Length of campaign	5 months*	
Location	Taiwan			
Image	Image provided by AXYS Technologies			
FLS	FLiDAR WindSentinel™			
LiDAR Type	ZephIR 300 LiDAR			
Purpose of Deployment	WRA.			
Description	LiDAR units were validated onshore to capture the required data range + offshore trial undertaken against met mast. Validation continues to prove useful as extended SAT Internal Validation carried out by Ørsted.			
OWA Roadmap Maturity Claim	N/A			
Operational	Successful deployment			
experience	Good co-operation from	n site team.		
	Tech challenges overcome with relative efficiency.			
	Supplier open to adaptions to Ørsteds Specifications.			
Resources	Deployment details and	d experiences con	tributed by Ørsted.	

4.2 SEAZEPHIR

FLS OEM: SeaRoc

LiDAR Type: ZephIR 300 LiDAR

<u>Deployments</u>

Ref	Deployment Date	Duration (months)	Location	Campaign Type
D15	November 2009	1	S. Coast Norway	Proof of concept
D16	March 2011	1	Block Island, Rhode Island, USA	Trial
D17	November 2014	24	GSOE, Delaware, USA	WRA

D15. SeaZephIR Norway Concept Trial, 2009

FLS OEM	SeaRoc	Other organisations	Natural Power (validating party)		
Start/End Date	November 2009 – unknown	Length of campaign	1 month (assumed)		
Location	800m off the south coa	ast of Norway			
Image	800m off the south coast of Norway				
FLS	SeaZephIR				
LiDAR Type	ZephIR 300 LiDAR				
Purpose of Deployment	Proof of concept				
Description	Concept trial: two ZephIR units deployed off coast of Norway, LandZephIR on small island and SeaZephIR buoy anchored out to sea. Separation 800m.				
OWA Roadmap Maturity Claim	N/A (pre-roadmap)				
Operational experience	Excellent correlation obtained between SeaZephIR and LandZephIR.				
Resources	Wind LiDAR Innovation	s presentation [R	14]		

D16. SeaZephIR Block Island Trial, 2009

FLS OEM	SeaRoc	Other organisations	Deepwater Wind (developer)	
Start/End Date	March 2011 – April 2011	Length of campaign	1 month	
Location	Block Island, Rhode Isla	ind, USA		
Image				
	Image taken from the E	Block Island Times	article [R16]	
FLS	SeaZephIR			
LiDAR Type	ZephIR 300 LiDAR			
Purpose of Deployment	Trial			
Description	The FLS was being trialled to use for wind farm development in the area. [R15]			
OWA Roadmap Maturity Claim	N/A (pre-roadmap)			
Operational experience	There was a structural failure three weeks in and the FLS tipped over [R16]			
Resources	Wind LiDAR Innovations presentation [R14]			

D17. SeaZephIR GSOE WRA, 2012

FLS OEM	SeaRoc	Other organisations	GSOE (developer)
Start/End Date	November 2012 – November 2014	Length of campaign	24 months
Location	Garden State Offshore Energy, Delaware, USA		
Image	No image available		
FLS	SeaZephIR		
LiDAR Type	ZephIR 300 LiDAR		
Purpose of Deployment	WRA		
Description	Following its previous deployment at Block Island, the SeaZephIR underwent several structural design changes and was re-deployed 23 miles off the coast of Atlantic City to support GSOE's planned offshore wind farm. [R17]		
OWA Roadmap Maturity Claim	N/A (pre-roadmap)		
Operational experience	N/A		
Resources	North American Clean Energy Press release [R17]		

4.3 AXYS FLIDAR 4M

FLS OEM: AXYS Technologies Inc. FLiDAR was originally launched in November 2012 by 3E and OWA and was acquired by AXYS in 2015 [R18].

LiDAR Type: Supports both Leosphere WINDCUBE®v2 LIDAR and ZephIR 300 LiDAR.

Greyed-out rows indicate known deployments where further detail cannot be provided due to commercial sensitivity.

Ongoing deployments as of February 2018 are marked with an asterisk (*). The duration reported in these cases is the number of months from the deployment date to February 2018.

Deployments

Ref	Deployment Date	Duration (months)	Location	Campaign Type
D18	September 2011	1	North Sea, Belgium	Proof of concept
D19	October 2012	3	Gwynt-y-Môr wind farm zone, Irish Sea, UK	Trial
D20	June 2013	15	Burbo Bank Extension wind farm zone, Irish Sea, UK	WRA
D21	January 2014	3	NAREC, Blyth, UK	Pre-deployment Trial
D22	April 2014	10	Walney Extension, Irish Sea	WRA
D23	April 2014	12	Neart na Gaoithe wind farm zone, North Sea, UK	WRA
	May 2015	2	Fécamp, France	Trial
	July 2015	14	Courseulles-sur-Mer, France	WRA
	July 2015	4	Fécamp, France	Trial
	October 2015	12	UK	WRA
	November 2016	3	Fécamp, France Trial	
	December 2017	2*	Provence Grand Large, France	WRA

D18. FLiDAR Proof of concept, North Sea, 2011

FLS OEM	FLIDAR	Other organisations	
Start/End Date	September – October, 2011	Length of campaign	1 month
Location	North Sea, Belgium		
Image	Image taken from press re	lease [R19]	
FLS	FLIDAR™ (prototype)		
LiDAR Type	WINDCUBE®v2 LIDAR from Leosphere		
Deployment purpose	Proof of concept		
Description	Early validation of FLiDAR prototype 15 km of the coast of Belgium. Data validated against fixed WINDCUBE LiDAR device on an offshore communication mast close to the test site.		
OWA Roadmap Maturity Claim	N/A (Pre-Roadmap)		
Operational experience	N/A		
Resources	offshoreWIND Press Release [R19]		
	3E News Press Release [R2	0]	

D19. FLiDAR Trial, Gwynt-y-Môr, 2012-2013

FLS OEM	FLIDAR	Other organisations	RWE OWA, Carbon Trust, Frazer-Nash Consultancy DNV GL
Start/End Date	October 2012 - January 2013	Length of campaign	3 months
Location	Gwynt-y-Môr wind farm zo	one, Irish Sea, UK	
Image	LIDAR Trial in the Irish Sea		ts and Findings of a OWA Floating
FLS	FLIDAR™ (prototype)		
LiDAR Type	WINDCUBE®v2 LIDAR from Leosphere		
Purpose of Deployment	Trial		
Description	Validation against Gwynt y Môr meteorological mast in the Irish Sea, which includes Measnet-calibrated cup anemometers at 90m and 50m above LAT and a wind vane at 70m. A Waverider buoy was also deployed during the trial.		
OWA Roadmap Maturity Claim	N/A (Pre-Roadmap)		
Operational experience	N/A		
Resources	OWA, Carbon Trust Results and Findings of an OWA Floating LIDAR Trial in the Irish Sea [R21]		

D20. FLiDAR 4M WRA, Burbo Bank, 2013-2014

FLS OEM	FLIDAR	Other organisations	Ørsted
Start/End Date	June 2013 – September 2014	Length of campaign	15 months
Location	Burbo Bank Extension wind	d farm zone, Irish	Sea, UK
Image	Image taken from Offshore	eWIND press relea	ase [R22]
FLS	FLIDAR 4M		
LiDAR Type	WINDCUBE®v2 LIDAR from Leosphere		
Purpose of Deployment	WRA with post-validation		
Description	"A FLiDAR buoy was the only device measuring the offshore wind resource on site from June 2013 to September 2014. It subsequently completed a final period of post validation against an offshore met mast." [R22]		
OWA Roadmap Maturity Claim	N/A		
Operational experience	N/A		
Resources	OffshoreWIND.biz press ro	elease [R22]	

D21. FLiDAR 4M Trial, NAREC, 2014

FLS OEM	FLiDAR	Other organisations	DNV GL (Validating party)
Start/End Date	January 2014 – April 2014	Length of campaign	3 months
Location	NAREC Met. Mast, Blyth, UK		
Image			
	Image taken from Carbon Trust press release [R23]		
FLS	FLIDAR 4M		
LiDAR Type	WINDCUBE®v2 LIDAR from Leosphere		
Purpose of Deployment	Trial		
Description	The FLS was validated by DNV GL before being used for a WRA for the Neart na Gaoithe wind farm zone [D23].		
OWA Roadmap Maturity Claim	Stage 2 maturity independently reported		
Operational experience	N/A		
Resources	Carbon Trust OWA press release [R23]		

D22. FLiDAR 4M WRA, Walney Extension, 2014-2015

FLS OEM	AXYS Technologies Inc.	Other organisations	Ørsted
Start/End Date	April 2014 – February 2015	Length of campaign	10 months
Location	Walney Extension	wind farm zone, Iri	ish Sea, UK
Image		NorCOWE press re	lease [R25]
FLS	FLIDAR™ 4M		
LiDAR Type	WINDCUBE®v2 LIDAR from Leosphere		
Purpose of Deployment	Wind resource assessment with post-validation		
Description	N/A		
OWA Roadmap Maturity Claim	N/A		
Operational experience	N/A		
Resources	NorCOWE press release [R25].		

D23. FLiDAR 4M WRA, Neart Na Gaoithe, 2014

FLS OEM	FLIDAR	Other organisations	Mainstream Renewable Power		
Start/End Date	April 2014 – March 2015	Length of campaign	12 months		
Location	Neart na Gaoithe	(NNG) wind farm zo	one, North Sea, UK (WRA)		
Image					
FLS	FLIDAR 4M				
LiDAR Type	WINDCUBE®v2 LII	DAR from Leospher	e		
Purpose of Deployment	WRA				
Description	A WRA was undertaken at NNG following a pre-deployment validation at the NAREC Met. Mast off the coast of Blyth [D21].				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	MAINSTREAM pro	ess release [R24]			

4.4 EOLOS FLS200

FLS OEM: EOLOS

LiDAR Type: ZephIR 300 LIDAR

Ongoing deployments as of February 2018 are marked with an asterisk (*). The duration reported in these cases is the number of months from the deployment date to February 2018.

Deployments

Ref	Deployment Date	Duration (months)	Location	Campaign Type
D24	May 2013	3	Spain, Mediterranean Sea	Proof of concept
D25	March 2015	6	Ijmuiden wind farm zone, North Sea, Netherlands	Trial
D26	January 2017	13	St Brieuc, France	WRA
D27	October 2017	1	National Renewable Energy Centre (NAREC), North Sea	Trial
D28	January 2018	1*	Bàltica III, Poland (40km from shore)	WRA

D24. EOLOS FLS200 Neptune Project, 2013

FLS OEM	EOLOS	Other	University of Stuttgart	
		organisations	Gas Natural Fenosa	
			Catalonia Institute of Energy Research	
			Technical University of Catalonia	
Start/End Date	May 2013 – July 2013	Length of campaign	3 months	
Location	Spain (Mediterrar	nean Sea), 250m fi	rom shore	
Image	Image taken from	Tackling of offsho	the current challenges are wind assessments.	
FLS	FLS200			
LiDAR Type	Zephir 300			
Purpose of Deployment	Proof of concept			
Description	the coast of Barce design-validation from a nearby pie installed. This cor the moving (LiDAF	elona, in north-east campaign. The b r, where an identi nfiguration allowe	of EOLOS buoy was deployed 250 meters off stern Spain, for an 8 week measurement and uoy was anchored at a distance of 50 meters ical calibrated ZephIR 300 LiDAR was d to take simultaneous measurements from LiDAR systems.	
OWA Roadmap Maturity Claim	N/A			
Operational experience	Excellent correlati	ion between the t	wo LiDAR types.	
Resources	EOLOS Validation	for CT Roadmap [R27]	
	EOLOS Neptune B	rochure [R26]		

D25. EOLOS FLS200 Ijmuiden Trial, 2015

FLS OEM	EOLOS	Other organisations	ECN (Validation party) RWE Innogy B.V (Client)
Start/End Date	March 2015 – October 2015	Length of campaign	6 months
Location	Ijmuiden wind farm zoi	ne, North Sea, Net	therlands
Image	Image taken from ECN	press release [R28	8]
FLS	FLS200		
LiDAR Type	Zephir 300		
Purpose of Deployment	Trial		
Description	"Last October 2015, the EOLOS FLS200 successfully completed a 6-month validation campaign next to the IEC-compliant Ijmuiden offshore meteorological mast in the North Sea. The campaign has been carried out in collaboration with RWE Innogy and under the framework of, and supported by, the OWA, Carbon Trust, as well as the Dutch R&D programme FLOW." [R28]		
OWA Roadmap Maturity Claim	Stage 2 maturity indep	endently reported	
Operational experience	N/A		
Resources	EOLOS Validation for CT Roadmap [R27]		
	ECN press release [R28]	

D26. EOLOS FLS200 St Brieuc WRA, 2017-2018

FLS OEM	EOLOS	Other organisations	Scottish Power Renewables	
Start/End Date	January 2017 – February 2018	Length of campaign	13 months	
Location	St Brieuc, France			
Image	Image provided by EOL	OS.		
FLS	FLS200			
LiDAR Type	Zephir 300			
Purpose of Deployment	WRA			
Description	Bound for Baltic Sea project for PGE after Blyth deployment. Pre-validation before commercial campaign in Baltic Sea.			
OWA Roadmap Maturity Claim	N/A			
Operational experience	N/A			
Resources	Deployment details cor	ntributed by Iberd	lrola.	

D27. EOLOS FLS200 NAREC Trial, 2017

FLS OEM	EOLOS	Other organisations			
Start/End Date	October 2017 –	Length of	1 month		
	November 2017	campaign			
Location	NAREC, North Sea				
Image	Image provided by EOLOS.				
FLS	FLS200				
LiDAR Type	Zephir 300				
Purpose of Deployment	Trial				
Description	Bound for Baltic Sea project for PGE after Blyth deployment. Pre-validation before commercial campaign in Baltic Sea.				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	EOLOS Validation for C	T Roadmap [R27]			

D28. EOLOS FLS200 Bàltica III WRA, 2017-2019

EOLOS	Other organisations			
January 2018 – 2019 (anticipated)	Length of campaign	1 month*		
Bàltica III, Poland (40kn	n from shore)			
FLS200				
Zephir 300				
WRA				
N/A				
N/A				
N/A				
EOLOS Validation for C	T Roadmap [R27]			
	January 2018 – 2019 (anticipated) Bàltica III, Poland (40kn Image provided by EOL FLS200 Zephir 300 WRA N/A N/A N/A	January 2018 – 2019 (anticipated) Length of campaign Bàltica III, Poland (40km from shore) Image provided by EOLOS. FLS200 Zephir 300 WRA N/A N/A		

^{*} The duration reported is the number of months from the deployment date to February 2018.

4.5 DEEPCLIDAR

FLS OEM: University of Maine

LiDAR Type: WINDCUBE®v2 LIDAR from Leosphere

<u>Deployments</u>

Ref	Deployment Date	Duration (months)	Location	Campaign Type
D29	June 2013	18	Gulf of Maine, USA	Trial
D30	May 2016	5	Gulf of Maine, USA	Trial

D29. DeepCLiDAR Trial, Maine, 2013

FLS OEM	University of Maine	Other organisations	AWS Truepower (validating party) NRG Systems Inc.		
Start/End Date	June 2013 – November 2014	Length of campaign	18 months		
Location	Gulf of Maine, USA				
Image	No image available				
FLS	DeepCLiDAR				
LiDAR Type	WINDCUBE®v2 LIDAR f	WINDCUBE®v2 LIDAR from Leosphere			
Purpose of Deployment	Trial				
Description	N/A				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	University of Maine Ne	ws [R29]			

D30. DeepCLiDAR Trial, Maine, 2016

FLS OEM	University of Maine	Other organisations	AWS Truepower (validating party)	
Start/End Date	May 2016 – October 2016	Length of campaign	5 months	
Location	Gulf of Maine, USA			
Image	THE WAINE			
FLS	DeepCLiDAR			
LiDAR Type	WINDCUBE®v2 LIDAR from Leosphere			
Purpose of Deployment	Trial			
Description	"The recent 5-month test concluded a robust, three-phase validation program that sequentially vetted the DeepCLiDAR's performance onshore, near-shore and offshore. The validation campaign was jointly developed by AWS Truepower and UMaine to characterize the floating LiDAR's measurements in the absence of an offshore meteorological tower. The basis for the system's evaluation and acceptance were the Key Performance Indicators and Acceptance Criteria defined by the OWA and Carbon Trust.			
OWA Roadmap Maturity Claim	Stage 2 maturity indep	endently reported		
Operational experience	N/A			
Resources	University of Maine Ne	ws [R30]		

4.6 FRAUNHOFER IWES WIND LIDAR BUOY

FLS OEM: Fraunhofer IWES

LiDAR Type: Supports both Leosphere WINDCUBE®v2 and ZephIR 300 LiDAR.

Ongoing deployments as of February 2018 are marked with an asterisk (*). The duration reported in these cases is the number of months from the deployment date to February 2018.

Deployments

Ref.	Deployment Date	Duration (months)	Location	Campaign Type
D31	August 2013	2	FINO1 Met. Mast, North Sea, Germany	Trial
D32	August 2014	1	FINO1 Met. Mast, North Sea, Germany	Trial
D33	January 2015	3	FINO1 Met. Mast, North Sea, Germany	Trial
D34	June 2015	3	FINO1 Met. Mast, North Sea, Germany	Trial
D35	July 2015	2	FINO1 Met. Mast, North Sea, Germany	Trial
D36	November 2015	6	Danish West Coast, North Sea	WRA
D37	February 2016	6	FINO1 Met. Mast, North Sea, Germany	Trial
D38	November 2016	6	FINO3 Met. Mast, North Sea, Germany	Trial
D39	March 2017	11*	Scottish East coast, UK	WRA
D40	December 2017	2*	Kincardine OWF, Scotland	WRA

D31. Fraunhofer WINDCUBE v2 Trial, 2013

FLS OEM	Fraunhofer IWES	Other organisations			
Start/End Date	August 2013 – October 2013	Length of campaign	2 months		
Location	FINO1 Met. Mast, Gern	nan Bight, North S	Sea		
Image	Image taken from Frau	nhofer IWES repo	ort [R31]		
FLS	Fraunhofer IWES Wind LiDAR Buoy				
LiDAR Type	WINDCUBE®v2 LIDAR f	rom Leosphere			
Purpose of Deployment	Trial				
Description	"Tested accuracy of wind measurements by Fraunhofer IWES Wind LiDAR Buoy in intended environment, 45 km offshore in 450 m distance to FINO1 met. mast (German Bight, North Sea)" [R31]				
OWA Roadmap Maturity Claim	N/A (Pre-Roadmap)				
Operational experience	N/A				
Resources	Offshore Wind Resource Assessment with Fraunhofer IWES Wind LiDAR Buoy [R31]				
	Gottschal et al. (2014)	[R32]			

D32. Fraunhofer ZephIR 300 Trial, 2014

FLS OEM	Fraunhofer IWES	Other organisations	ZephIR
Start/End Date	August 2014 – September 2014	Length of campaign	1 month
Start/End Date	August 2014 – Septeml	per 2014	
Location	FINO1 Met. Mast, Gern	nan Bight, North S	Sea
Image			
FLS	Image taken from ZephIR LiDAR press release [R33] Fraunhofer IWES Wind LiDAR Buoy		
LiDAR Type	ZephIR 300		
Purpose of Deployment	Trial		
Description	Wind LiDAR Buoy now mast, in the German No Borkum. Both the avail assessed against the of comparison adhering to	equipped with a Zorth Sea about 45 ability and the accifshore test site who IEC 61400-12-1 cmast are compare	med for and with the Fraunhofer IWES ZephIR 300 LiDAR next to the FINO1 met km north of the East Frisian island curacy of the floating lidar system were hich was set up as a lidar-mast ed.2 CD where wind measurements and with each other for different the conditions." [R33]
OWA Roadmap Maturity Claim	N/A		
Operational experience	N/A		
Resources	ZephIR LiDAR press rel	ease [R33]	

D33. Fraunhofer WINDCUBE v2 Trial, 2015

FLS OEM	Fraunhofer IWES	Other organisations	DNV GL (Reviewing party)	
Start/End Date	January 2015 - April 2015	Length of campaign	3 months	
Location	FINO1 Met. Mast, Gern	nan Bight, North S	Sea	
Image				
FLS	Fraunhofer IWES Wind	LiDAR Buoy		
LiDAR Type	WINDCUBE®v2 LIDAR f	rom Leosphere		
Purpose of Deployment	Trial			
Description	"DNV GL was asked by IWES to carry out an independent review of data from IWES LiDAR Buoy Validations at FINO1 and to provide written acknowledgment on the wind speed and wind direction accuracy results gained within these Trials with regards to the corresponding OWA/CT Roadmap KPI Acceptance Criteria [1]." [R34]			
OWA Roadmap Maturity Claim	Accuracy requirements for Stage 2 independently confirmed by DNV GL.			
Operational experience	N/A			
Resources	DNV GL Technical Note [R34]			

D34. Fraunhofer with ZephIR 300 LiDAR FINO1 Trial, 2015

FLS OEM	Fraunhofer IWES	Other organisations	OBLEX-F1 partners (incl. NORCOWE consortium)
Start/End Date	June 2015 - September 2015	Length of campaign	3 months
Location	FINO1 Met. Mast, Gern	nan Bight, North S	Sea
Image	Image taken from Fraunhofer Results Presentation [R35]		
FLS	Fraunhofer IWES Wind LiDAR Buoy		
LiDAR Type	ZephIR 300		
Purpose of Deployment	Trial		
Description	Two Fraunhofer FLS carrying different lidar types were measuring wind speed profiles up to 200 m as part of the met-ocean research campaign OBLEX-F1 campaign.		
OWA Roadmap Maturity Claim	N/A		
Operational experience	N/A		
Resources	Fraunhofer IWES Resu	Its presentation a	t OBLEX-F1 Workshop [R35]

D35. Fraunhofer with WINDCUBE®v2 LiDAR FINO1 Trial, 2015

FLS OEM	Fraunhofer IWES	Other organisations	OBLEX-F1 partners (incl. NORCOWE consortium)	
Start/End Date	July 2015 - September 2015	Length of campaign	2 months	
Location	FINO1 Met. Mast, Gern	nan Bight, North S	Sea	
Image				
FLS	Fraunhofer IWES Wind LiDAR Buoy			
LiDAR Type	WINDCUBE®v2 LIDAR f	rom Leosphere		
Purpose of Deployment	Trial			
Description	Two Fraunhofer FLS carrying different lidar types were measuring wind speed profiles up to 200 m as part of the met-ocean research campaign OBLEX-F1 campaign.			
OWA Roadmap Maturity Claim	N/A			
Operational experience	N/A			
Resources	Fraunhofer IWES Resul	lts presentation a	t OBLEX-F1 Workshop [R35]	

D36. Fraunhofer RUNE Measuring Campaign, 2015

FLS OEM	Fraunhofer IWES	er IWES Other organisations	Technical University of Denmark (DTU)	
			RUNE consortium	
	November 2015 -	Length of	6 months	
	April 2016	campaign		
Location	North Sea, Danish West	Coast		
Image	Traumotor. Branco			
FLS F	Fraunhofer IWES Wind LiDAR Buoy			
LiDAR Type	WINDCUBE®v2 LIDAR from Leosphere			
Purpose of Deployment	Measuring campaign			
	Used to support the RUNE research project (Reducing the Uncertainty of Nearshore wind resource estimate using onshore lidars) for DTU. Reference measurements of winds speed at heights of up to 250m were provided to support the project and to develop the use of floating LiDAR systems in a commercial environment.			
OWA Roadmap Maturity Claim	N/A			
•	Survived storm Freja one week after installation, experiencing significant wave heights up to 4.5m.			
Resources	Fraunhofer press release [R36]			

D37. Fraunhofer FINO1 Trial, 2016

FLS OEM	Fraunhofer IWES	Other	OWA, Carbon Trust
		organisations	ODSL for ORE Catapult (Validating party)
Start/End Date	February 2016 – August 2016	Length of campaign	6 months
Location	FINO1 Met. Mast, Gern	nan Bight, North S	Sea
Image	Image provided by Frau	unhofer IWES	
FLS	Fraunhofer IWES Wind LiDAR Buoy		
LiDAR Type	ZephIR 300		
Purpose of Deployment	Trial		
Description	"ORE Catapult Development Services has carried out an independent verification of Frauhofer IWES' Floating LiDAR System Verification Trial in accordance with the new OWA Recommended Practices for Floating LiDAR Systems. The Fraunhofer IWES Floating LiDAR Buoy was found to meet the highest, "Best Practice", criteria within the "OWA Roadmap for Floating LiDAR Systems" and the "OWA Recommended Practices for Floating LiDAR Systems" for all wind speed and direction metrics." [R39]		
OWA Roadmap Maturity Claim	Stage 2 maturity indepo	endently reported	1
Operational experience	N/A		
Resources	ORE Catapult Floating L	iDAR System Veri	fication Report [R39]

D38. Fraunhofer WINDCUBE®v2 Trial, 2016

FLS OEM	Fraunhofer IWES	Other organisations	DNV-GL (Validating party)	
Start/End Date	November 2016 – June 2017	Length of campaign	6 months	
Location	FINO3 Met. Mast, Gern	nan Bight, North S	Sea	
Image				
FLS	Fraunhofer IWES Wind	LiDAR Buoy		
LiDAR Type	WINDCUBE®v2 LIDAR f	rom Leosphere		
Purpose of Deployment	Trial			
Description	Dedicated 6-month tria	l for buoy with se	cond LiDAR system.	
OWA Roadmap Maturity Claim	Stage 2 maturity independently reported			
Operational experience	N/A			
Resources	DNV GL Independent A	ssessment Report	: [R40]	

D39. Fraunhofer Firth of Forth WRA, 2017

FLS OEM	Fraunhofer IWES	Other organisations	Seagreen Wind Energy Ltd (developer)
Start/End Date	March 2017 – March 2019 (anticipated)	Length of campaign	11 months*
Location	Firth of Forth, Scotland		
Image	Image taken from Frau	nhofer Press Rele	ase [R41]
FLS	Fraunhofer IWES Wind LiDAR Buoy		
LiDAR Type	ZephIR 300		
Purpose of Deployment	WRA		
Description	"The project from Seagreen Wind Energy Ltd encompasses a 12 to 24 month measuring campaign during which the LiDAR buoy will measure wind speeds at different heights of up to 650 feet using laser remote sensing." [R41]		
OWA Roadmap Maturity Claim	N/A		
Operational experience	Smooth preparations and installation - see [R41]		
Resources	Fraunhofer IWES Press	Release [R41]	

^{*} The duration reported is the number of months from the deployment date to February 2018.

D40. Fraunhofer Kincardine WRA, 2017

FLS OEM	Fraunhofer IWES	Other organisations			
Start/End Date	December 2017 – December 2018 (anticipated)	Length of campaign	2 months*		
Location	Kincardine OWF, Scotla	nd			
Image	Image provided by Fraunhofer IWES				
FLS	Fraunhofer IWES Wind LiDAR Buoy				
LiDAR Type	WINDCUBE®v2 LIDAR fi	rom Leosphere			
Purpose of Deployment	WRA				
Description	A wind resource assessment for the Kincardine OWF project.				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	gov.scot Notice to Mari	gov.scot Notice to Mariners [R42]			

^{*} The duration reported is the number of months from the deployment date to February 2018.

4.7 NASS&WIND M3EA

FLS OEM: Nass&Wind Smart Services

LiDAR Type: Leosphere WINDCUBE®v2 OFFSHORE 8.66

Ongoing deployments as of February 2018 are marked with an asterisk (*). The duration reported in these cases is the number of months from the deployment date to February 2018.

Deployments

Ref.	Deployment Date	Duration (months)	Location	Campaign Type
D41	January 2014	11	Saint Marcouf Island, France	Trial
D42	May 2016	21*	Dunkirk, France	WRA

D41. Nass&Wind M³EA Trial, Saint Marcouf, 2014

FLS OEM	Nass&Wind Smart Services	Other organisations	DNV GL (Validating party)
Start/End Date	January 2014 – December 2014	Length of campaign	11 months
Location	Saint Marcouf Islands,	Channel, North of	France
Image	Image courtesy of Nass	&Wind Smart Ser	vices
FLS	M ³ EA		Vices
LiDAR Type	WINDCUBE®v2 Offshore LIDAR from Leosphere		
Purpose of Deployment	Trial		
Description	WINDCUBE®v2 Offshor	e LiDAR used as a	reference.
OWA Roadmap Maturity Claim	Based on the results of this validation, DNV GL considers that the uncertainty associated with horizontal wind speed measurements undertaken by M3EA as a standalone source of wind data would be in the higher range of the indicative uncertainty of Stage 2: "Pre-commercial". However, as an offshore LiDAR was used as a reference (as opposed to an offshore metmast as specified in the OWA Roadmap). The M3EA Floating LiDAR device type is not considered to be within Stage 2.		
Operational experience	Broad validation envelope obtained (including wind speed, significant wave heights, current speed)		
	 Two major outages occurred due to memory card issues, resulting in missing data. 		
Resources	Nass&Wind Oceanolog	y International pr	esentation [R45]
	WINDPOWER OFFSHOR	RE Press Release [R44]
	Nass&Wind with DNV GL EWEA Poster [R45]		
	Details provided by Nass&Wind Smart Services.		

D42. Nass&Wind M³EA WRA, Dunkirk, 2016

FLS OEM	Nass&Wind Smart Services	Other organisations			
Start/End Date	May 2016 - ongoing	Length of campaign	21 months*		
Location	Dunkirk, France				
Image	Image taken from Offshore Wind Industry [R46]				
FLS	M ³ EA				
LiDAR Type	WINDCUBE®v2 Offshor	e LIDAR from Leo	sphere		
Purpose of Deployment	WRA	WRA			
Description	Wind measurement ca	Wind measurement campaign for the OWF project off Dunkirk			
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	Offshore Wind Industry Press Release [R46]				
	Deployment details and experiences contributed by Nass&Wind.				

^{*} The duration reported is the number of months from the deployment date to February 2018.

4.8 FUGRO OCEANOR SEAWATCH

FLS OEM: Fugro Oceanor (Norway)

LiDAR Type: ZephIR 300 LiDAR (M or M equivalent)

Ongoing deployments as of February 2018 are marked with an asterisk (*). The duration reported in these cases is the number of months from the deployment date to February 2018.

Deployments

Ref.	Deployment Date	Duration (months)	Location	Buoy ID	Campaign Type
D43	April 2014	7	Ijmuiden Met. Mast, North Sea, Netherlands	WS140	Trial
D44	February 2015	12	Navitus Bay offshore wind farm, UK	WS140	WRA
D45	March 2015	1	Titran, Frøya, Norway	WS149	Trial
D46	June 2015	3	Titran, Frøya, Norway	WS156	Trial
D47	June 2015	18	Borssele Lot 1, The Netherlands	WS149, WS156, WS157	WRA
D48	November 2015	7	East Anglia ONE Met. Mast, UK	WS155	Trial
D49	December 2015	1	Titran, Frøya, Norway	WS157	Trial
D50	February 2016	5	Borssele Lot 2, The Netherlands	WS156	WRA
D51	April 2016	1	Titran, Frøya, Norway	WS158	Trial
D52	May 2016	3	Titran, Frøya, Norway	WS140	Trial
D53	June 2016	20*	Hollandse Kust zuid, The Netherlands	WS140, WS155, WS158	WRA
D54	January 2017	1	Titran, Frøya, Norway	WS159	Trial
D55	January 2017	13*	Baltica 3, Poland	WS155, WS159	WRA
D56	March 2017	1	Titran, Frøya, Norway	WS170	Trial
D57	March 2017	1	Titran, Frøya, Norway	WS171	Trial
D58	April 2017	10*	Hollandse Kust noord, The Netherlands	WS149, WS155, WS170	WRA
D59	May 2017	9*	East Anglia THREE, UK	WS171	WRA
D60	July 2017	3	Hornsea Met. Mast, UK	WS172, WS173	Trial
D61	October 2017	4*	Hornsea, UK	WS172, WS173	WRA

D43. Fugro SEAWATCH WS140 Trial, 2014

FLS OEM	Fugro	Other organisations	Ecofys (Validating party) ECN (Reviewing party) DNV GL (Data analysis) ENECO, OWA, Carbon Trust	
Start/End Date	April 2014 – November 2014	Length of campaign	7 months	
Start/End Date	April 2014 – November	2014		
Location	Ijmuiden Met. Mast, No	orth Sea, Netherla	ands	
Image	Image taken from Ecofy	ys Uncertainty Ass	sessment [R47]	
FLS	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS140)	
LiDAR Type	ZephIR 300			
Purpose of Deployment	Trial			
Description	The FLS was validated against the RWE IJmuiden Offshore Met Mast, located 80km off the Dutch coast.			
OWA Roadmap Maturity Claim	Stage 2 maturity indepo	endently reported		
Operational experience	The campaign originally began in January 2014 but failed, and was re-deployed in April 2014.			
Resources	Ecofys Uncertainty Asse	essment [R47]		
	DNV GL Assessment [R4	48]		

D44. Fugro SEAWATCH WS140 Navitus Bay WRA, 2015

FLS OEM	Fugro	Other organisations	EDF Energy (developer)		
Start/End Date	February 2015 – January 2016	Length of campaign	12 months		
Location	Navitus Bay offshore w	ind farm, English	Channel, UK		
Image	Image taken from WINDPOWER Offshore press release [R49]				
FLS	OCEANOR SEAWATCH	wing LIDAK buoy	(WS140)		
LiDAR Type	ZephIR 300				
Purpose of Deployment	WRA				
Description	The project was stopped by a decision in the British Parliament 11 Sept 2015. Fugro Norway (OCEANOR) decided to keep the buoy in position as long as there was fuel left. This was until end of year 2015 and the buoy was recovered in early 2016. Pre-deployment validated [D43]				
OWA Roadmap Maturity Claim	N/A				
Operational experience	Good availability				
Resources	WINDPOWER Offshore press release [R49]				
	Deployment details contributed by Fugro.				

D45. Fugro SEAWATCH WS149 Pre-deployment Trial, 2015

FLS OEM	Fugro	Other organisations	DNV GL (Validating party)		
Start/End Date	March 2015	Length of campaign	1 month		
Location	Titran, Frøya, Norway				
Image	Image taken from DNV GL Assessment [R50]				
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS149)				
LiDAR Type	ZephIR 300				
Purpose of Deployment	Trial				
Description	Buoy WS149 completed a pre-deployment Trial before performing a WRA at Borssele Lot 1 [D47].				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	DNV GL Validation repo	DNV GL Validation report [R50]			

D46. Fugro SEAWATCH WS156 Pre-deployment Trial, 2015

FLS OEM	Fugro	Other organisations	DNV GL (Validating party)		
Start/End Date	June 2015 – September 2015	Length of campaign	3 months		
Location	Titran, Frøya, Norway				
Image					
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS156)				
LiDAR Type	ZephIR 300				
Purpose of Deployment	Trial				
Description	Buoy WS156 completed a pre-deployment Trial before performing a WRA at Borssele Lot 1 [D47].				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	DNV GL Validation report [R51]				

D47. Fugro SEAWATCH WRA, Borssele Lot 1, 2015 - 2017

FLS OEM	Fugro	Other organisations	Ørsted (developer)		
Start/End Date	June 2015 – February 2017	Length of campaign	18 months		
Location	Borssele Lot 1, The Net	herlands			
Image	No image available				
FLS	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS149)		
	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS156)		
	OCEANOR SEAWATCH Wind LiDAR buoy (WS157)				
LiDAR Type	ZephIR 300				
Purpose of Deployment	WRA				
Description	Pre-deployment validated (Buoys WS149, WS156 and WS157 validated by DNV GL [D45], [D46], [D49])				
OWA Roadmap Maturity Claim	N/A				
Operational	Excellent availability after February 2016				
experience	Initially, LiDAR was not marinized and suffered a corrosion problem.				
Resources	Deployment details and experiences contributed by Fugro.				

D48. Fugro SEAWATCH WS155 Trial, 2015-2016

FLS OEM	Fugro	Other organisations	Scottish Power Renewables (developer) Natural Power (Validating party) OWA, Carbon Trust		
Start/End Date	November 2015 – June 2016	Length of campaign	7 months		
Location	East Anglia ONE Me	t. Mast, UK			
Image	Image taken from o	ffshoreWIND pre	ss release [R52]		
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS155)				
LiDAR Type	ZephIR 300				
Purpose of Deployment	Trial				
Description	Part of the Carbon	Trust OWA LiDAR	validation campaign [R37].		
	Good results for the	e KPI's both for w	ind speed and wind direction.		
OWA Roadmap Maturity Claim	Stage 2 maturity independently reported				
Operational experience	 Excellent availability in late stages Smooth towing Initial issue with corrosion of the communications cable causing a data loss of nearly 50%. 				
Resources	offshoreWIND pres	ss release [R52]			
	4coffshore press re	lease [R53]			
	Deployment details	and experiences	contributed by Fugro and Iberdrola.		

D49. Fugro SEAWATCH WS157 Pre-deployment Trial, 2015-2016

FLS OEM	Fugro	Other organisations	DNV GL (Validating party)		
Start/End Date	December 2015 – January 2016	Length of campaign	1 month		
Location	Titran, Frøya, Norway				
Image	Image taken from DNV GL Validation report [R54]				
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS157)				
LiDAR Type	ZephIR 300				
Purpose of Deployment	Trial				
Description	Buoy WS157 completed a pre-deployment Trial before performing a WRA at Borssele Lot 1 [D47]. WS157 was deployed at a later stage in the WRA than buoys WS149 and WS156.				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	DNV GL Validation report [R54]				

D50. Fugro SEAWATCH WRA, Borssele Lot 2, 2016

FLS OEM	Fugro	Other organisations	Ørsted (developer)	
Start/End Date	February 2016 – June 2016	Length of campaign	5 months	
Location	Borssele Lot 2, The Net	herlands		
Image	No image available			
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS156)			
LiDAR Type	ZephIR 300			
Purpose of Deployment	WRA			
Description	Pre-deployment validated [D46]			
OWA Roadmap Maturity Claim	N/A			
Operational experience	Excellent availability			
Resources	Deployment details and experiences contributed by Fugro.			

D51. Fugro SEAWATCH WS158 Pre-deployment Trial, 2016

FLS OEM	Fugro	Other organisations	DNV GL (Validating party)		
Start/End Date	April 2016 – May 2016	Length of campaign	1 month		
Location	Titran, Frøya, Norway				
Image					
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS158)				
LiDAR Type	ZephIR 300				
Purpose of Deployment	Trial				
Description	Buoy WS158 completed a pre-deployment Trial before performing a WRA at Hollandse Kust zuid [D53].				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	DNV GL Validation report [R56]				

D52. Fugro SEAWATCH WS140 Pre-deployment Trial, 2016

FLS OEM	Fugro	Other organisations	DNV GL (Validating party)		
Start/End Date	May 2016 – August 2016	Length of campaign	3 months		
Location	Titran, Frøya, Norway				
Image	Image taken from DNV				
FLS	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS140)		
LiDAR Type	ZephIR 300				
Purpose of Deployment	Trial				
Description	Buoy WS140 completed a pre-deployment Trial before performing a WRA Hollandse Kust zuid [D53]				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	DNV GL Validation repo	ort [R56]			

D53. Fugro SEAWATCH Hollandse Kust zuid WRA, 2016 - 2018

FLS OEM	Fugro	Other organisations	Ørsted (developer)		
Start/End Date	June 2016 – June 2018 (anticipated)	Length of campaign	20 months*		
Location	Hollandse Kust zuid, Th	e Netherlands			
Image	No image available				
FLS	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS140)		
	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS155)		
	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS158)		
LiDAR Type	ZephIR 300				
Purpose of Deployment	WRA				
Description	Commercial WRA and r	net-ocean measu	rements.		
	Pre-deployment validated				
OWA Roadmap Maturity Claim	N/A				
Operational	Good availability				
experience	Good data accuracy				
	One incident where a vessel cut the mooring.				
Resources	Deployment details and experiences contributed by Fugro.				

^{*} The duration reported is the number of months from the deployment date to February 2018.

D54. Fugro SEAWATCH WS159 Pre-deployment Trial, 2017

FLS OEM	Fugro	Other organisations	DNV GL (Validating party)
Start/End Date	January 2017 – February 2017	Length of campaign	1 month
Location	Titran, Frøya, Norway		
Image	No image available		
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS159)		
LiDAR Type	ZephIR 300 LiDAR		
Purpose of Deployment	Trial		
Description	Buoy WS159 completed a pre-deployment Trial before performing a WRA at Baltica 3 [D55].		
OWA Roadmap Maturity Claim	N/A		
Operational experience	N/A		
Resources	Deployment details and experiences contributed by Fugro.		

D55. Fugro SEAWATCH Baltica 3 WRA, 2017 - 2019

FLS OEM	Fugro	Other organisations		
Start/End Date	January 2017 – February 2019 (anticipated)	Length of campaign	13 months*	
Location	Baltica 3, Poland			
Image	No image available			
FLS	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS155)	
	OCEANOR SEAWATCH Wind LiDAR buoy (WS159)			
LiDAR Type	ZephIR 300			
Purpose of Deployment	WRA			
Description	Commercial WRA and met-ocean measurements.			
	Pre-deployment validated (WS155 [D48], WS159 [D54]).			
OWA Roadmap Maturity Claim	N/A			
Operational experience	Good availability			
Resources	Deployment details and experiences contributed by Fugro.			

^{*} The duration reported is the number of months from the deployment date to February 2018.

D56. Fugro SEAWATCH WS170 Pre-deployment Trial, 2017

FLS OEM	Fugro	Other organisations	DNV GL (Validating party)		
Start/End Date	March 2017	Length of campaign	1 month		
Location	Titran, Frøya, Norway				
Image					
FLS	OCEANOR SEAWATCH	Image taken from DNV GL Validation Report [R57] OCEANOR SEAWATCH Wind LiDAR buoy (WS170)			
LiDAR Type	ZephIR 300M				
Purpose of Deployment	Trial				
Description	Buoy WS170 completed a pre-deployment Trial before performing a WRA at Hollandse Kust Noord [D58]				
OWA Roadmap Maturity Claim	N/A				
Operational experience	N/A				
Resources	DNV GL Validation Report [R57]				
	Deployment details and	d experiences con	tributed by Fugro.		

D57. Fugro SEAWATCH WS171 Trial, 2017

FLS OEM	Fugro	Other organisations	DNV GL (Validating party)	
Start/End Date	March 2017 – April 2017	Length of campaign	1 month	
Location	Titran, Frøya, Norway	Titran, Frøya, Norway		
Image	No image available			
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS171)			
LiDAR Type	ZephIR 300M	ZephIR 300M		
Purpose of Deployment	Trial			
Description	N/A			
OWA Roadmap Maturity Claim	N/A			
Operational experience	N/A			
Resources	Deployment details and experiences contributed by Fugro.			

D58. Fugro SEAWATCH Hollandse Kust noord WRA, 2017 - 2018

FLS OEM	Fugro	Other organisations		
Start/End Date	April 2017 – April 2018	Length of campaign	10 months*	
Location	Baltik III, Norway			
Image	No image available			
FLS	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS149)	
	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS155)	
	OCEANOR SEAWATCH Wind LiDAR buoy (WS170)			
LiDAR Type	ZephIR 300M or M equivalent			
Purpose of Deployment	WRA			
Description	Commercial WRA and met-ocean measurements.			
	Buoys WS149, WS155 and WS170 pre-deployment validated by DNV GL ([D45], [D48], [D56] respectively)			
OWA Roadmap Maturity Claim	N/A			
Operational	Good availability			
experience	Good data accurac	у		
Resources	Deployment details and experiences contributed by Fugro.			

^{*} The duration reported is the number of months from the deployment date to February 2018.

D59. Fugro SEAWATCH East Anglia THREE WRA, 2017 - 2018

FLS OEM	Fugro	Other organisations	Scottish Power Renewables (developer)
Start/End Date	May 2017 – May 2018 (anticipated)	Length of campaign	9 months*
Location	East Anglia THREE, UK		
Image	No image available		
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS171)		
LiDAR Type	ZephIR 300M		
Purpose of Deployment	WRA		
Description	Commercial WRA and met-ocean measurements.		
	Buoy was pre-deployment validated [D56]		
OWA Roadmap Maturity Claim	N/A		
Operational experience	Good availability		
Resources	Deployment details and experiences contributed by Fugro.		

^{*} The duration reported is the number of months from the deployment date to February 2018.

D60. Fugro SEAWATCH Hornsea Trial, 2017

FLS OEM	Fugro	Other organisations	Ørsted (developer)		
Start/End Date	July 2017 – September 2017	Length of campaign	3 months		
Location	Hornsea Met. Mast, UK				
Image	No image available				
FLS	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS172)		
	OCEANOR SEAWATCH	Wind LiDAR buoy	(WS173)		
LiDAR Type	ZephIR 300M				
Purpose of Deployment	Trial				
Description	LiDAR units were validated onshore to capture the required data range and offshore trial undertaken against met mast. This work was part of FLS contract. Internal Validation carried out by Ørsted.				
OWA Roadmap Maturity Claim	N/A				
Operational	Successful deployment.				
experience	Good co-operation from	Good co-operation from site team.			
	Quick manufacture & d	lelivery time.			
	Using field engineers fr	om multiple locat	ions.		
	Supplier open to adaptions of SWLB to Ørsteds Specifications.				
	Some challenges with directional measurements - OWA KPI's achieved but was a degree of scatter remaining.				
Resources	Details contributed by Ørsted.				

D61. Fugro SEAWATCH Hornsea WRA, 2018-2019

FLS OEM	Fugro	Other organisations	Ørsted (developer)	
Start/End Date	October 2017 – October 2018 (anticipated)	Length of campaign	4 months*	
Location	Hornsea, UK			
Image	No image available			
FLS	OCEANOR SEAWATCH Wind LiDAR buoy (WS172) OCEANOR SEAWATCH Wind LiDAR buoy (WS173)			
LiDAR Type	ZephIR 300M			
Purpose of Deployment	WRA			
Description	Commercial WRA and met-ocean measurements. Buoys were pre-deployment validated by DNV GL.			
OWA Roadmap Maturity Claim	N/A			
Operational experience	N/A – Future deployment			
Resources	Details contributed by Fugro.			

^{*} The duration reported is the number of months from the deployment date to February 2018.

4.9 BABCOCK FORECAST

FLS OEM: Babcock

LiDAR Type: Zephir 300 LiDAR

<u>Deployments</u>

Ref.	Deployment Date	Duration (months)	Location	Campaign Type
D62	May 2014	6	Gwynt-y-Môr wind farm zone, Irish Sea, UK	Trial
D63	October 2016	15	Aberdeen Offshore Wind Farm (EOWDC), Scotland	WRA

D62. Babcock FORECAST Trial, Gwynt-y-Môr, 2013-2015

FLS OEM	Babcock	Other organisations	RWE OWA, Carbon Trust, Frazer-Nash Consultancy DNV GL
Start/End Date	May 2014 – November 2014	Length of campaign	6 months
Location	Gwynt-y-Môr wind farr	m zone, Irish Sea,	UK
Image	Image taken from Zeph	IR LiDAR press re	lease [R58]
FLS	FORECAST		
LiDAR Type	Zephir 300		
Purpose of Deployment	Trial		
Description	•	ns were tested. T	r 2013 for an initial development phase he validation then began in August 2014 onths [R58].
	Part of the Carbon Trus	t OWA LiDAR vali	dation campaign [R37].
OWA Roadmap Maturity Claim	Stage 2 maturity indep	endently reported	d
Resources	ZephIR LiDAR press rele	ease [R58]	
	Carbon Trust OWA Floa	nting LiDAR Camp	aign: Babcock trial at Gwynt Y Môr [R59]
Operational experience	N/A		

D63. Babcock FORECAST WRA, EOWDC 2016 - 2018

FLS OEM	Babcock	Other organisations	Vattenfall (Wind farm owner) Aberdeen Offshore Wind Farm Ltd	
Start/End Date	October 2016 – January 2018	Length of campaign	15 months	
Location	Aberdeen Offshore Wir	nd Farm (EOWDC)	, Scotland	
Image	Image taken from offshoreWIND press release [R60]			
FLS	FORECAST	FORECAST		
LiDAR Type	Zephir 300 LiDAR			
Purpose of Deployment	WRA			
Description	Previously validated at Gwynt-y-Môr [D62] as part of the Carbon Trust's OWA LiDAR validation campaign [R37].			
OWA Roadmap Maturity Claim	N/A			
Operational	Installation went well a	nd the power sys	tem and buoy performed well.	
experience	Some problems reporte	ed with the data l	ogger and memory issue on LiDAR.	
Resources	Offshore wind press release [R60]			
	Deployment details and	d experiences con	tributed by Vattenfall.	

4.10 SEALIDAR

D64. seaLIDAR Trial, Greece, 2015

FLS OEM	seaLIDAR	Other organisations	
Start/End Date	July 2015	Length of campaign	Unknown
Location	Thermaikos Gulf, Greed	ce	
Image	seaLIDAR		
FLS	seaLIDAR		
LiDAR Type	ZephIR 300 LIDAR		
Purpose of Deployment	Trial		
Description	N/A		
OWA Roadmap Maturity Claim	N/A		
Operational experience	N/A		
Resources	Windpower Engineerin	g & Development	press release [R61]

4.11 ACCURASEA - EOLFI SPAR BUOY

D65. Eolfi Spar FLS, Le Planier Test campaign, 2016-2017

FLS OEM	Eolfi	Other organisations	NKE Instrumentation Ifremer, IRSEEM Wood Group
Start/End Date	May 2016 – September 2017	Length of campaign	17 months
Location	Le Planier, France		
Image	Deployment of the Blidar buoy at Le pLanier EOIFI Image courtesy of Eolfi		
FLS	Spar Floating LiDAR System		
LiDAR Type	Mitsubishi Diabrezza		
Purpose of Deployment	Test campaign, wind data collection		
Description	Part of the BLIDAR campaign. The new FLS system completed a 17 month test campaign and results will be certified by Wood Group, an independent third party. A second measurement campaign is planned to validate the FLS against the Roadmap. [R62]		
OWA Roadmap Maturity Claim	N/A		
Operational	Good overall system availability		
experience	Installation/retrieval of the buoy went well		
	Good buoy robustness and stability		
	Good quality and availability of wind speed and direction measurements (In accordance with the Acceptance Criteria from the OWA Roadmap)		
Resources	OffshoreWIND Press Release [R62]		
	Deployment details and experiences contributed by EOLFI.		

4.12 AKROCEAN WINDSEA

FLS OEM: AKROCEAN

LiDAR Type: Leosphere WINDCUBE®v2 LIDAR, Zephir 300

Ongoing deployments as of February 2018 are marked with an asterisk (*). The duration reported in these cases is the number of months from the deployment date to February 2018.

Deployments

Ref.	Deployment Date	Duration (months)	Location	Campaign Type
D66	July 2017	7*	Oléron Island, France	WRA
D67	March 2018	Not started	Fécamp Met. Mast	Trial

D66. AKROCEAN WINDSEA Oléron Island WRA, 2017-2018

FLS OEM	AKROCEAN	Other organisations	Meteo France (developer)
Start/End Date	July 2017 – September 2018 (anticipated)	Length of campaign	7 months*
Location	Oléron Island, France		
Image	Change Settler Set is the road		
FLS	Image provided by AKROCEAN. WINDSEA		
LiDAR Type	Leosphere WINDCUBE®v2 LIDAR		
Purpose of Deployment	WRA		
Description	A one-year wind assessment campaign for Meteo France		
OWA Roadmap Maturity Claim	N/A		
Operational	Pre-commissioning and installation went smoothly		
experience	Good LiDAR measurements availability and quality (excellent correlation with METEO France wind models)		
	Good collaboration with maintenance teams and supervision centre and good working conditions on-site		
	Sea state complicated sinker deployment		
	Effective response from secondary power systems following a failure of the main power allowed a quick recovery and re-deployment (system fully functional again after <30 hours)		
	Minor problems with data reconstruction with 3D motion compensation algorithm while raw data were OK. Software update solved the problem.		
Resources	AKROCEAN presentation [R63]		
	Deployment details and experiences contributed by AKROCEAN.		

^{*} The duration reported is the number of months from the deployment date to February 2018.

D67. AKROCEAN WINDSEA Trial, 2018

FLS OEM	AKROCEAN	Other organisations	DNV GL
Start/End Date	March 2018 – October 2018 (anticipated)	Length of campaign	Not yet started
Location	Northern Europe Onshore Met. Mast and Fécamp offshore Met. Mast		
Image	Image provided by AKROCEAN.		
FLS	WINDSEA		
LiDAR Type	Leosphere WINDCUBE®v2 LIDAR + ZephIR 300 LiDAR		
Purpose of Deployment	Trial		
Description	Type 2 validation deployment with dual LIDAR		
	Offshore trials reviewed by DNV GL		
OWA Roadmap Maturity Claim	N/A – Future deployment		
Operational experience	N/A – Future deployment		
Resources	AKROCEAN presentation [R63]		
	Deployment details and	d experiences con	tributed by AKROCEAN.

4.13 DEWI WITH LEOSPHERE

D68. DEWI Lightship based FLS, Trial 2017-2018

FLS OEM	DEWI by UL international	Other organisations	
Start/End Date	August 2017 – ongoing	Length of campaign	5 months*
Location	German Bight, North Sea		
Image	No image available		
FLS	Wind LiDAR on a lightship (moored) + AHRS/GPS sensors		
LiDAR Type	WINDCUBE V2		
Purpose of Deployment	Trial		
Description	Comparison with a wind LiDAR at Helgoland Island (WindCube WLS8-8)		
OWA Roadmap Maturity Claim	Unknown		
Operational experience	No problems reported		
Resources	Presented at DEWEK17 conference		

^{*} The duration reported is the number of months from the deployment date to February 2018.

5. DEPLOYMENTS BY LOCATION

In this section, various map views are provided to allow an appreciation of the geographical distribution of FLS deployments. Please note that a small number of deployments are not shown in the map views due to commercial sensitivity at the time of writing.

5.1 ALL LOCATIONS



Figure 2: Locations of all deployments. Image produced using Leaflet © OpenStreetMap.

5.2 IRISH SEA, NORTH SEA

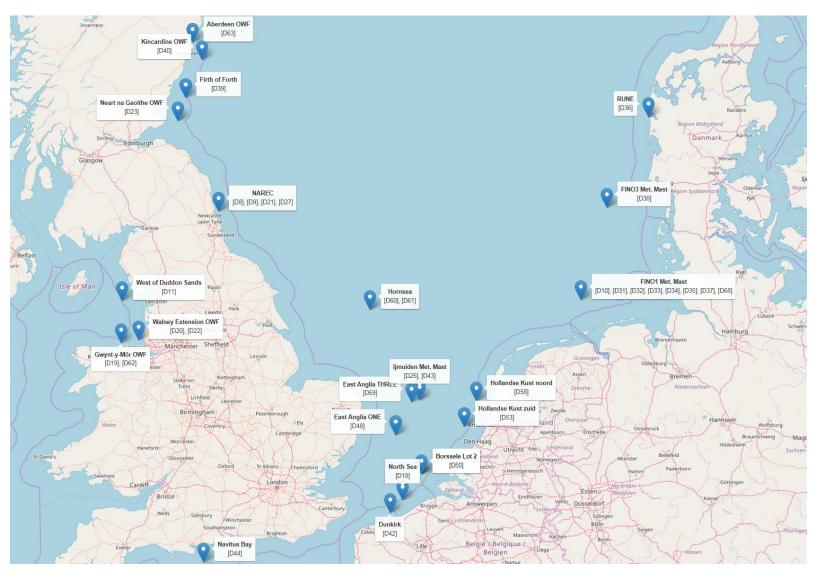


Figure 3: Locations of deployments in the Irish Sea and North Sea. Image produced using Leaflet © OpenStreetMap.

5.3 SOUTHWEST EUROPE

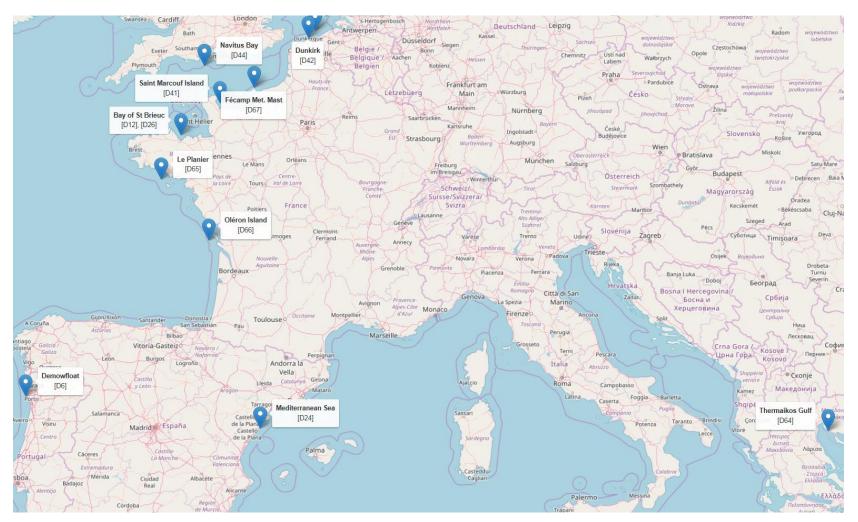


Figure 4: Locations of deployments off the coasts of France and Portugal and in the Mediterranean Sea. Image produced using Leaflet © OpenStreetMap.

5.4 USA

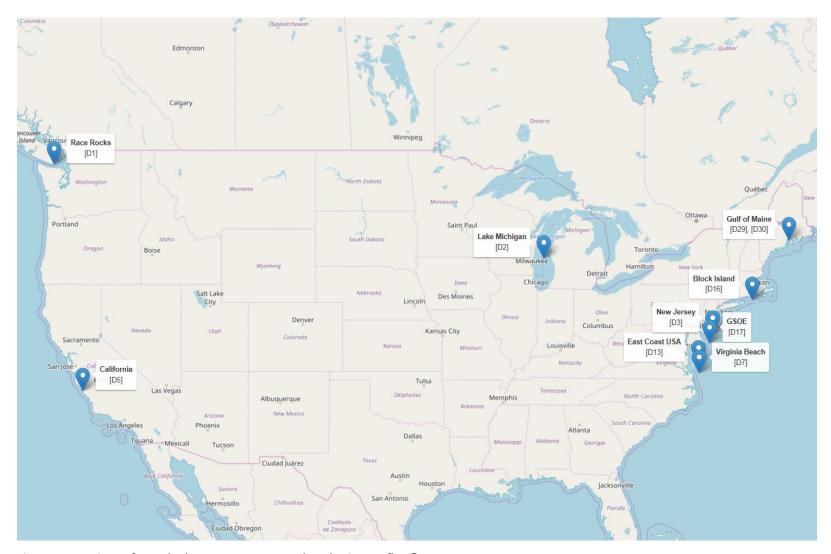


Figure 5: Locations of USA deployments. Image produced using Leaflet © OpenStreetMap.

5.5 BALTIC AND NORWEGIAN SEA

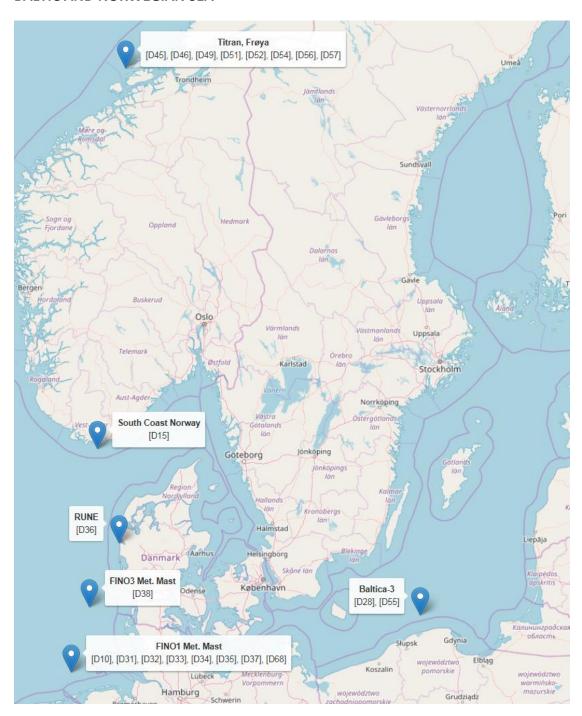


Figure 6: Locations of deployments in the Baltic and Norwegian Sea. Image produced using Leaflet @ OpenStreetMap.

6. GENERAL OPERATIONAL EXPERIENCE FEEDBACK

As part of the research conducted to compile this document, the operational experiences and problems encountered by FLS users were obtained from a variety of sources. A number of items are included in the list of deployments (Section 4). In many cases stakeholders made more general statements or did not wish to attribute deployment issues to particular deployments due to commercial sensitivities. To aid future FLS developments and updates to the Roadmap these experiences are listed anonymously in this section. Entries have been edited for brevity.

- Hardware damage due to sea state, drifting debris or other vessels.
- Water ingress to electronics causing systems to malfunction and communication problems.
- On-board power generation being insufficient for offshore applications.
- Damage caused during deployment (dropping buoy on deck) or by equipment (e.g. collision with crane, entanglement of mooring and tow lines, failures in lines).
- Rusting and corrosion.
- Inoperative wind turbines, solar panels or other power supply components.
- Tangling and breakage of mooring lines, in some cases due to fishing activities.
- Vandalism to the FLS including theft.
- Failure of memory units.
- Failure of communication links and hardware.
- Availability of vessels complying with the health and safety standards of validating parties.

7. REFERENCES

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